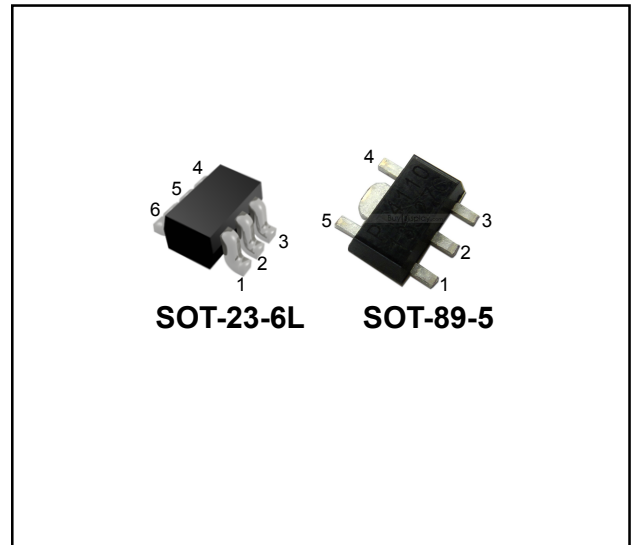


**PWM CONTROL STEP-UP SWITCHING REGULATOR**

**FEATURES**

- Low Start-up Input Voltage: 0.9V @  $I_{OUT} = 1mA$
- 1MHz Fixed Switching Frequency
- 90% Efficiency
- High Supply Capability to Deliver 3.3V/300mA with One Alkaline Cell or Deliver 5V/1.1A with One Li-ion Cell
- 17 $\mu$ A Quiescent (Switch-off) Supply Current
- 0.01 $\mu$ A Shutdown Mode Supply Current
- Providing Flexibility for Using Internal Power Switches
- Output Voltage: Settable to Between 2.0V to 6.0V, Accuracy of 2%

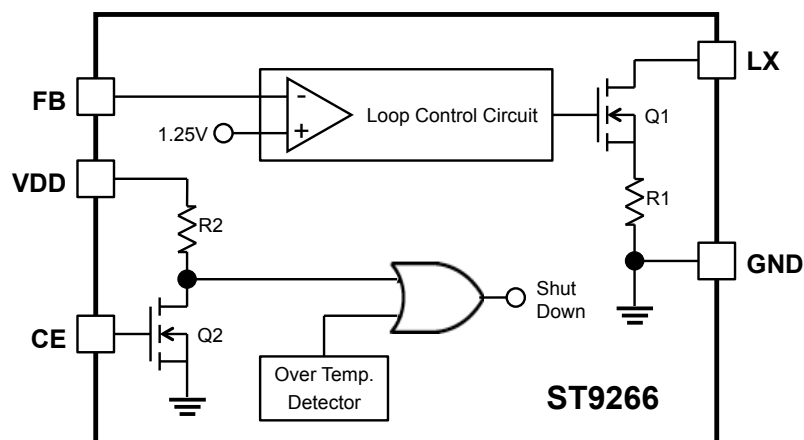


**DESCRIPTION**

The **STComponent** ST9266 is a compact, high efficiency, and low voltage step-up DC/DC converter with an Adaptive Current Mode PWM control loop, includes an error amplifier, ramp generator, comparator, switch pass element and driver in which providing a stable and high efficient operation over a wide range of load currents. It operates in stable waveforms without external compensation.

The low start-up input voltage below 0.9V makes ST9266 suitable for 1 to 4 battery cells applications of providing up to 1.1A output current. Besides, the 17 $\mu$ A low quiescent current together with high efficiency maintains long battery lifetime. The output voltage is set with two external resistors.

**INTERNAL SCHEMATIC DIAGRAM**



**DEVICE SUMMARY**

Ordering Code	Pin Configuration						V <sub>FB</sub> Accuracy	Package Type	Shipping	Marking <sup>(1)</sup>
	CE	NC	GND	LX	VDD	FB				
ST9266A1MR	1	2	3	4	5	6	±1%	SOT-23-6L	Taping reel	<b>AA1X</b>
ST9266A2MR	1	2	3	4	5	6	±2%		Taping reel	<b>AA2X</b>
ST9266A1PR	1	-	5	4	2	3	±1%	SOT-89-5	Taping reel	<b>AX A1</b>
ST9266A2PR	1	-	5	4	2	3	±2%		Taping reel	<b>AX A2</b>

Note 1: X: Assembly lot number: 0 ~ 9, A ~ Z mirror writing. (G, I, J, O, Q, W exception)

**ABSOLUTE MAXIMUM RATINGS <sup>(2)</sup>**

T<sub>A</sub> = 25°C, all voltages respect to ground unless otherwise specified.

PARAMETER	SYMBOL	RATINGS	UNIT
Input Voltage	V <sub>DD</sub>	-0.3 ~ +7	V
Output Voltage	V <sub>OUT</sub>	-0.3 ~ +7	V
	V <sub>LX</sub>	-0.3 ~ +7	V
LX Pin Switch Current	I <sub>LX</sub>	2.5	A
Power Dissipation	P <sub>D</sub>	SOT-23-6L	150
		SOT-89-5	500
Operating Ambient Temperature	T <sub>opr</sub>	-40 ~ +80	°C
Storage Temperature Range	T <sub>stg</sub>	-65 ~ +150	°C

Note 2: Absolute Maximum Ratings are those values beyond which the device could be permanently damaged. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

**Thermal Data**

PARAMETER	SYMBOL	RATINGS	UNIT
Thermal Resistance, Junction-to-Case	R <sub>θJC</sub>	SOT-23-6L	145
		SOT-89-5	45

**ELECTRICAL CHARACTERISTICS**

$V_{IN} = 1.5V$ ,  $V_{DD}$  set to  $3.3V$ , Load current = 0,  $T_A = 25^{\circ}C$ , all tests refer to *Test Circuit* unless otherwise specified.

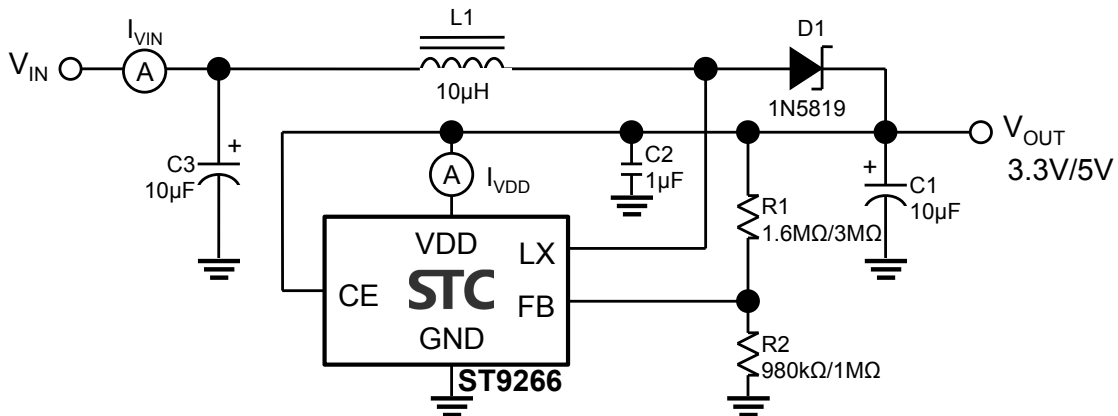
PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Operation Start Voltage	$V_{ST}$	$I_{OUT} = 1mA$		0.9	1.00	V
VDD Supply Voltage	$V_{DD}$	VDD pin voltage	2		6	V
Shutdown Current @ $I_{VIN}$	$I_{OFF}$	$CE = 0, V_{IN} = 4.5V$		0.01	1	$\mu A$
Switch-off Current @ $I_{VDD}$	$I_{switch-off}$	$V_{IN} = 6V$		17	25	$\mu A$
Continuous Switching Current	$I_{switch}$	$V_{IN} = CE = 3.3V, V_{FB} = GND$		500		$\mu A$
No Load Current @ $I_{VIN}$ <sup>(3)</sup>	$I_{no-load}$	$V_{IN} = 1.5V, V_{OUT} = 3.3V$		56		$\mu A$
Feedback Reference Voltage	$V_{FB}$	Close loop $V_{DD} = 3.3V$	1.225	1.250	1.275	V
Switching Frequency	$F_S$	$V_{DD} = 3.3V$	800	1000	1250	kHz
Maximum Duty	$D_{max}$	$V_{DD} = 3.3V$	70	75	80	%
LX On Resistance	$R_{LXon}$	$V_{DD} = 3.3V$		0.18	0.25	$\Omega$
Current Limit Setting <sup>(4)</sup>	$I_{limit}$	$V_{DD} = 3.3V$	2.3	2.5	2.7	A
Line Regulation	$\Delta V_{line}$	$V_{IN} = 3.5V \sim 6V, I_L = 1mA$		0.25	5	mV/V
Load Regulation <sup>(5)</sup>	$\Delta V_{load}$	$V_{IN} = 2.5V, I_L = 1mA \sim 100mA$		0.5		mV/mA
CE Pin Trip Level	$V_{CEtrip}$	$V_{DD} = 3.3V$	0.4	0.8	1.2	V
Temperature Stability for $V_{OUT}$	$T_S$			50		ppm/ $^{\circ}C$
Thermal Shutdown Hysteresis	$\Delta T_{sd}$			10		$^{\circ}C$

Note 3: *No Load Current* is highly dependent on practical system design and component selection that cannot be covered by production testing. Typical *No Load Current* is verified by typical application circuit with recommended components. *No Load Current* performance is guaranteed by *Switch-off Current* and *Continuous Switching Current*.

Note 4: Current limit is guaranteed by design at  $T_A = 25^{\circ}C$ .

Note 5: *Load Regulation* is not tested at production due to practical instrument limitation. *Load Regulation* performance is dominantly dependent on DC loop gain and *LX On Resistance* that are guaranteed by "*Line Regulation*" and "*LX On Resistance*" tests in production.

**TEST CIRCUIT**



## TYPICAL APPLICATION CIRCUIT

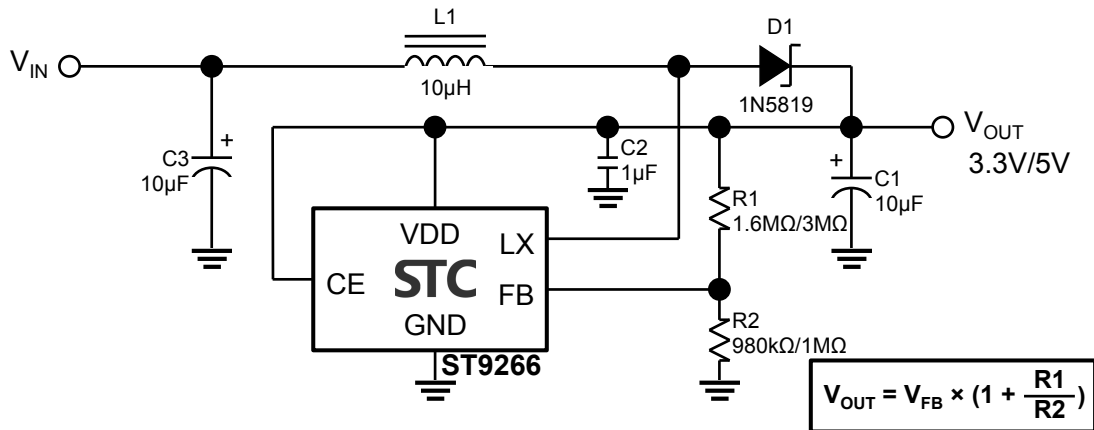


Figure 1: Typical Application for Portable Instruments

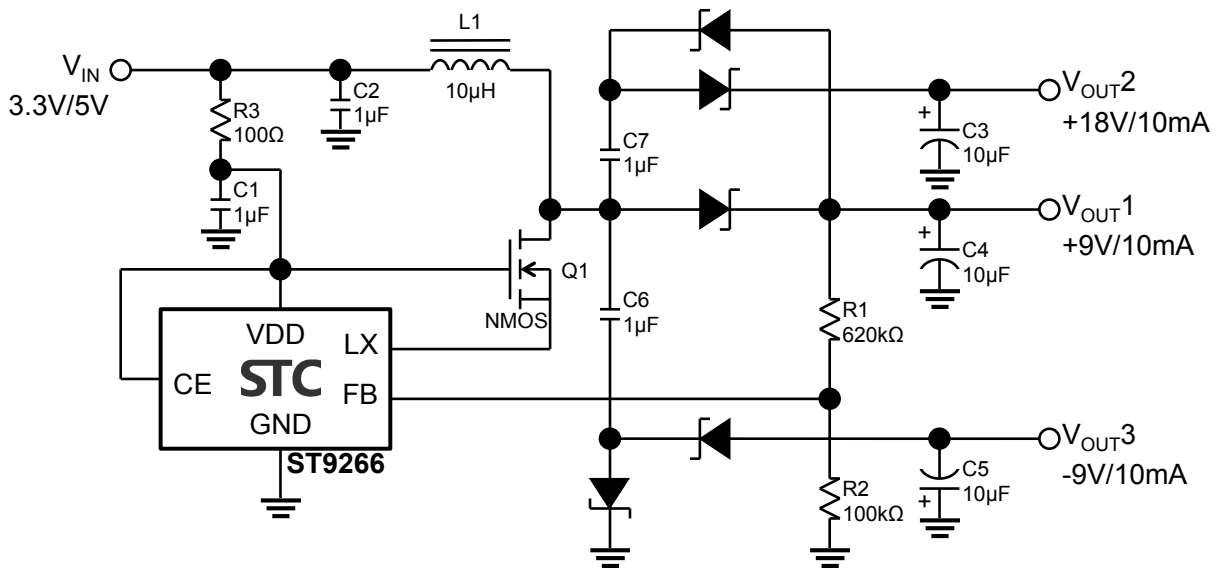
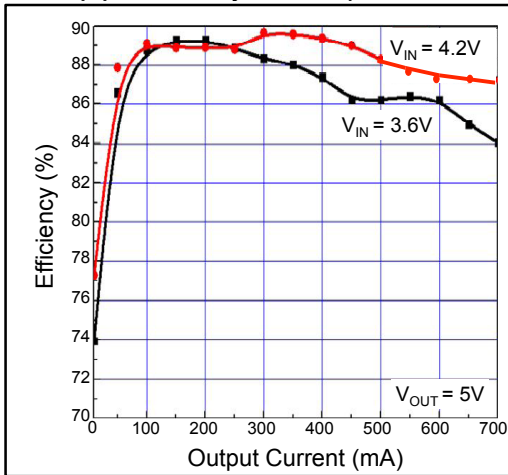


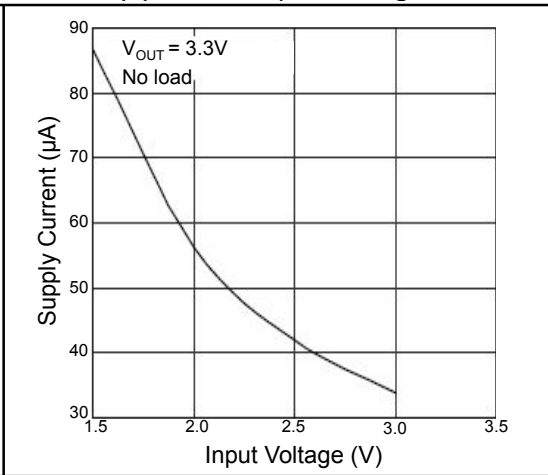
Figure 2: Multi-output Application

**ELECTRICAL CHARACTERISTICS CURVES**

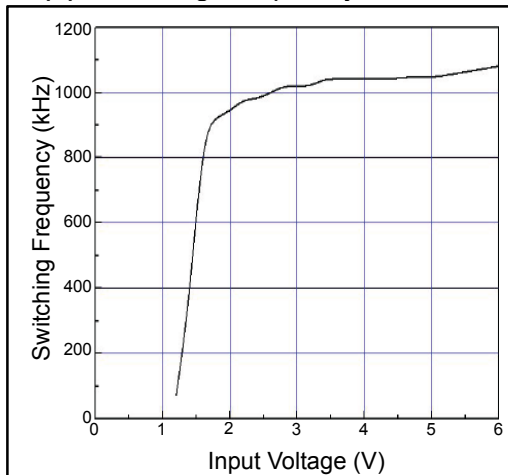
**(1) Efficiency vs. Output Current**



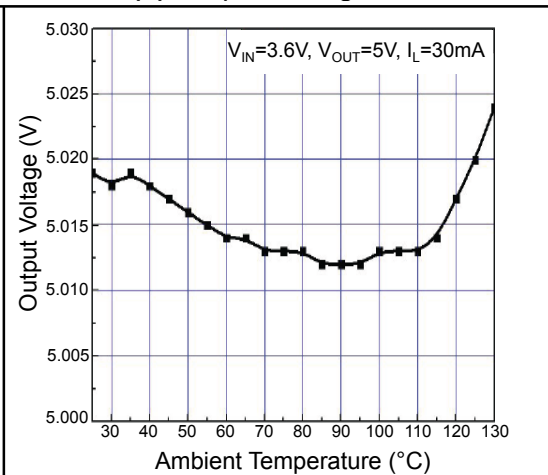
**(2)  $I_{VIN}$  vs. Input Voltage**



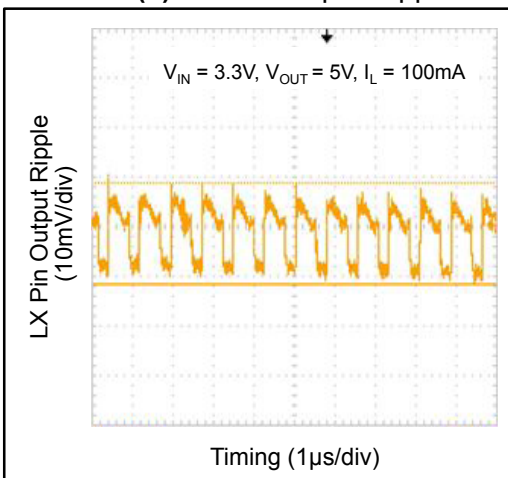
**(3) Switching Frequency vs. VDD Pin**



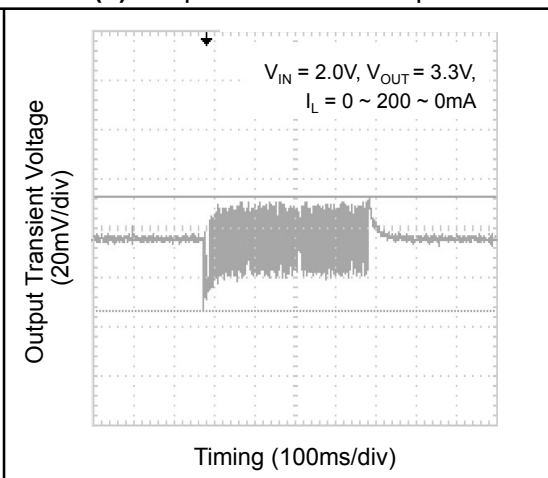
**(4) Output Voltage vs.  $T_A$**



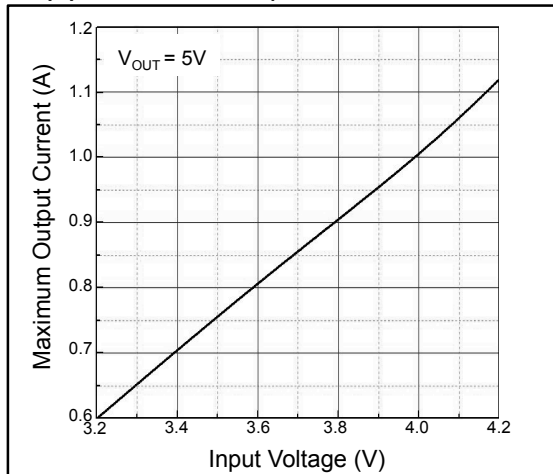
**(5) LX Pin Output Ripple**



**(6) Output Transient Response**



(7) Maximum Output Current vs.  $V_{IN}$



**APPLICATION INFORMATION**

**Output Voltage Setting**

Referring to *Typical Application Circuit*, the output voltage of the switching regulator ( $V_{OUT}$ ) can be set with Equation (1).

$$V_{OUT} = (1 + R1/R2) \times V_{FB} \tag{1}$$

**Feedback Loop Design**

Referring to *Typical Application Circuit*. The selection of R1 and R2 based on the trade-off between quiescent current consumption and interference immunity is stated below:

- Follow Equation (1)
- Higher R resistor reduces the quiescent current (Path current =  $1.25/R2$ ), however resistors beyond  $5M\Omega$  are not recommended.
- Lower R resistor gives better noise immunity, and is less sensitive to interference, layout parasitics, FB node leakage, and improper probing to FB pins.
- A proper value of feed forward capacitor parallel with R1 can improve the noise immunity of the feedback loops, especially in an improper layout. An empirical suggestion is around  $0 \sim 33pF$  for feedback resistors of  $M\Omega$ , and  $10nF \sim 0.1\mu F$  for feedback resistors of tens to hundreds  $k\Omega$ .

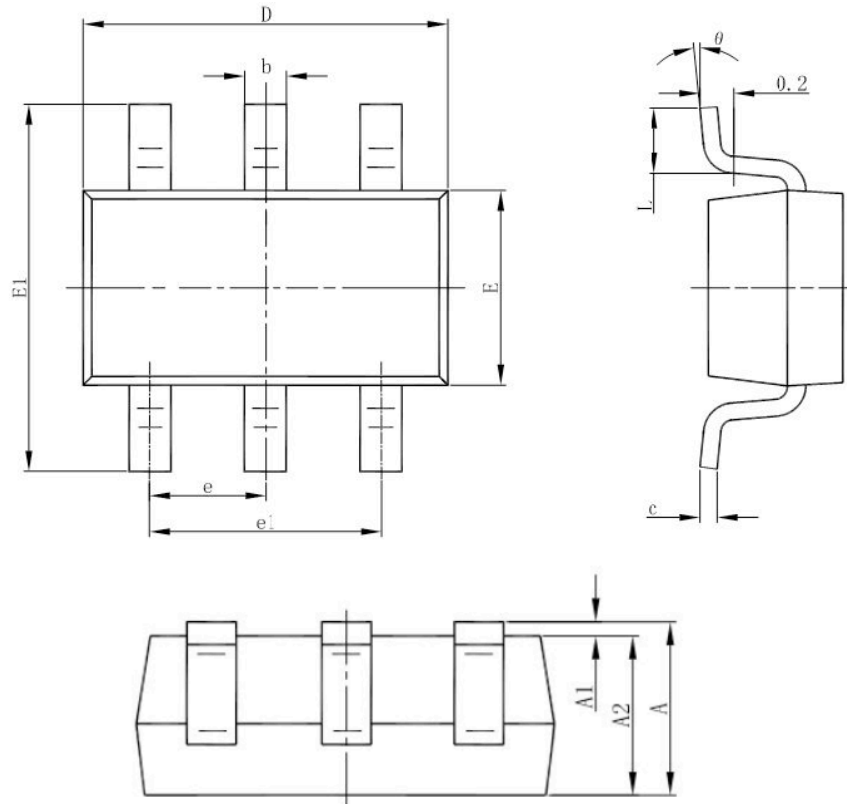
For applications without standby or suspend modes, lower values of R1 and R2 are preferred. For applications concerning the current consumption in standby or suspend modes, the higher values of R1 and R2 are needed.

**Layout Guide**

- A full GND plane without gap break.
- VDD to GND noise bypass – Short and wide connection for the 1 $\mu$ F MLCC capacitor between Pin 5 and Pin 3 (refer to SOT-23-6L pin assignment).
- V<sub>IN</sub> to GND noise bypass – Add a capacitor close to L1 inductor, when V<sub>IN</sub> is not an idea voltage source.
- Minimized FB node copper area and keep far away from noise source.
- Minimized parasitic capacitance connecting to LX nodes, which may cause additional switching loss.

**PACKAGE DIMENSION**

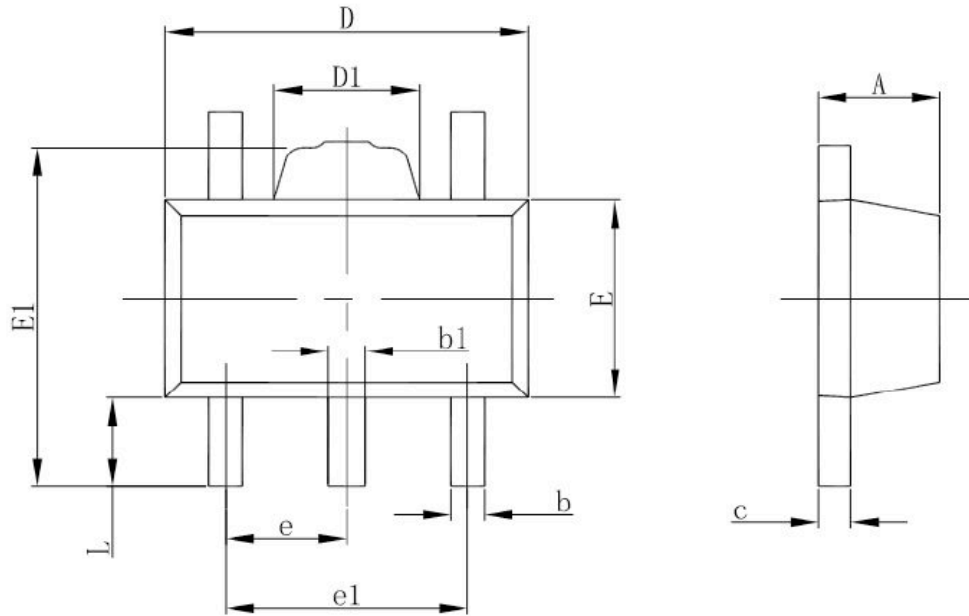
**SOT-23-6L**



SYMBOL	Dimensions in Millimeters		Dimensions in Inches	
	MIN	MAX	MIN	MAX
A	1.050	1.250	0.041	0.049
A1	0.000	0.100	0.000	0.004
A2	1.050	1.150	0.041	0.045
b	0.300	0.500	0.012	0.020
c	0.100	0.200	0.004	0.008
D	2.820	3.020	0.111	0.119
E	1.500	1.700	0.059	0.067
E1	2.650	2.950	0.104	0.116
e	0.950 (BSC)		0.037 (BSC)	
e1	1.800	2.000	0.071	0.079
L	0.300	0.600	0.012	0.024
$\theta$	0°	8°	0°	8°



**SOT-89-5**



SYMBOL	Dimensions in Millimeters		Dimensions in Inches	
	MIN	MAX	MIN	MAX
A	1.400	1.600	0.055	0.063
b	0.320	0.520	0.013	0.020
b1	0.360	0.560	0.014	0.022
c	0.350	0.440	0.014	0.017
D	4.400	4.600	0.173	0.181
D1	1.400	1.800	0.055	0.071
E	2.300	2.600	0.091	0.102
E1	3.940	4.250	0.155	0.167
e	1.500 (TYP)		0.060 (TYP)	
e1	2.900	3.100	0.114	0.122
L	0.900	1.100	0.035	0.043

**NOTICE**

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